



PROUCT NAME

TM58PE10

TITLE

Applications of TIMER Interrupt on TM58PE10

APPLICATION NOTE

1. Types of interrupt methods
2. Substantial descriptions of interrupt methods
3. Application circuits

There are three TIMER Interrupt methods in TM58PE10: TMR0 IRQ, TMR1 IRQ and TMR2 IRQ. In addition, TMR1 and TMR2 can be combined to form a 16-bit timer. To use the timer IRQ function, users must select the ADVANCED mode of the TM58 series IC since IRQ function is only available in the advanced mode. In the advanced mode, the interrupt vector is at 3FFH.

Descriptions of interrupt methods:

1. TMR0 Interrupt

There are two special function registers associated with its operation, namely the interrupt mask register IRQM (address 21H) and the interrupt flag register IRQF (address 22H). Their definitions are tabulated as follow:

IRQM:

Control register IRQM (21H)		
Address	Symbol	Description
7	INTM	Bit for enabling use: The priority of this bit is higher than other interrupt enabling signals. 1: Enable 0: Disable Note: When the "RETI" command is executed, it sets the address of "INTM" to 1.
6	----	Unused
5	TMR2M	TMR2 interrupt enable: 1: enable interrupted 0: disable interrupted
4	TMR1M	TMR1 interrupt enable: 1: enable interrupted 0: disable interrupted

3	----	Unused
2	EXINTM1	External interrupt enable PA5/RESETB1/INT1: 1: enable interrupted 0: disable interrupted
1	EXINTM0	External interrupt enable PA0/RESETB0/INT0: 1: enable interrupted 0: disable interrupted
0	TMR0M	TMR0 interrupt enable: 1: enable interrupted 0: disable interrupted

FIG. 6-10 Interrupt Mask Register (IRQM Register)

IRQM:

Control register IRQF (22H)		
Address	Symbol	Description
7~6	----	Unused
5	TMR2F	TMR2 interrupt flag: 1: The overflow of TMR2 timer generates an interrupt request.
4	TMR1F	TMR1 interrupt flag: 1: The overflow of TMR1 timer generates an interrupt request.
3	----	Unused
2	EXINTF1	External interrupt flag 1: 1: PA5/RESETB1/INT1 The change in the falling edge of the pin generates an interrupt request (NOTE<4>)
1	EXINTF0	External interrupt flag 0: 1: PA0/RESETB0/INT0 The change in the falling edge of the pin generates an interrupt request (NOTE<4>)
0	TMR0F	TMR0 interrupt flag: 1: The overflow of TMR0 timer generates an interrupt request.

FIG. 1-2 Interrupt Flag Register (IRQF Register)

NOTE:

- <1> TMR0 counts upwards and overflows when the value reaches 256.
The hardware will set TMR0F to 1 to enter interrupt.
- <2> One should pay attention, when programming, to the saving of variables when entering interrupt and the resuming of variables when exiting interrupt.
- <3> Primary interrupt generation time= $1/4M^4 \cdot t_{mr0} \text{ rate} \cdot (256 - t_{mr0} \text{ value})$ second.
- <4> The value of TMR0 should be reloaded when entering interrupt.

2. TMR1 interrupt

There are four special function registers (SFR) associated with its operation, namely the IRQM (Interrupt Mask Register, its address is 21H), the IRQF (Interrupt Flag Register, its address is 22H), TRM1Control, which is the control register of TMR1 (with the address of 24H), and TMR1Preload, which is the data register of TMR1 (with the address of 26H); SFRs are defined as follows:

TMR1Control:

Control register TMR1 Control (24H)					
Address	Symbol	Description			
7	TMR1EN	TMR1 enable input: 1: TMR1 enable 0: TMR1 disable			
6	LOAD	Timer1 data loading mode: 1: When data is being written into TMR1 Preload register (TMR1_PRELOAD, 26H), the content of TMR1 is loaded immediately (default). 0: When data is being written into TMR1 Preload register (TMR1_PRELOAD, 26H), its value is not loaded until there is a count overflow in TMR1.			
5	SUR1	SUR1	SUR0	TMR1 clock source	
		0	0	Sourced from system time (only applicable to internal RC or external RC)(NOTE<5>)	
		0	1	Sourced from EXT_CLK	
4	SUR0	1	0	Sourced from TMR2 (Connected to form a 16bit timer)	
		1	1	Not executed	
3	EDGE1	EDGE1: Sourced from the edge control bit in the source signal of system time. 1: When EXT_CLK signal changes from high → low, TMR1 plus 1 0: When EXT_CLK signal changes from low → high, TMR1 plus 1			
		PS2	PS1	PS0	TMR1 prescaling ratio
		0	0	0	1: 1
		0	0	1	1: 2
		0	1	0	1: 4
		0	1	1	1: 8
		1	0	0	1: 16
		1	0	1	1: 32
		1	1	0	1: 64
		1	1	1	1: 128

FIG. 1-3 TMR1 Control register

TMR1、TMR2 Preload:

Control register TMR1, TMR2 Preload register (26H, 27H)		
Address	Symbol	Description
7~0	D7~D0	TMR1 and TMR2 Preload data register. Default data value: D7~ D0 = FFH

NOTE:

- <1> TMR1 counts down, and data overflow occurs after the value becomes 00, then the hardware sets TMR1F to 1 in order to enter an interrupt.
- <2> During programming, special attention should be directed to the storage of variables when entering an interrupt; as well as the restoration of variables when exiting an interrupt.
- <3> The time for generating an interrupt = $1/4 * \text{tmr1 prescaler rate} * \text{tmr1 preload seconds}$
- <4> When entering an interrupt, the value of TMR1Preload does not need to be reloaded, the already defined value in the preload register will be automatically reloaded into the timer register.
- <5> The setting of Tmr1 data load mode for entering the TMR1Control register: when it is 1 (default) and there is data to be written into the register, the count value of TMR1 changes immediately. When it is 0 and there is data to be written into the register, the data can only be written into the register after a count overflow of TMR1 has occurred. As shown in the following diagram:

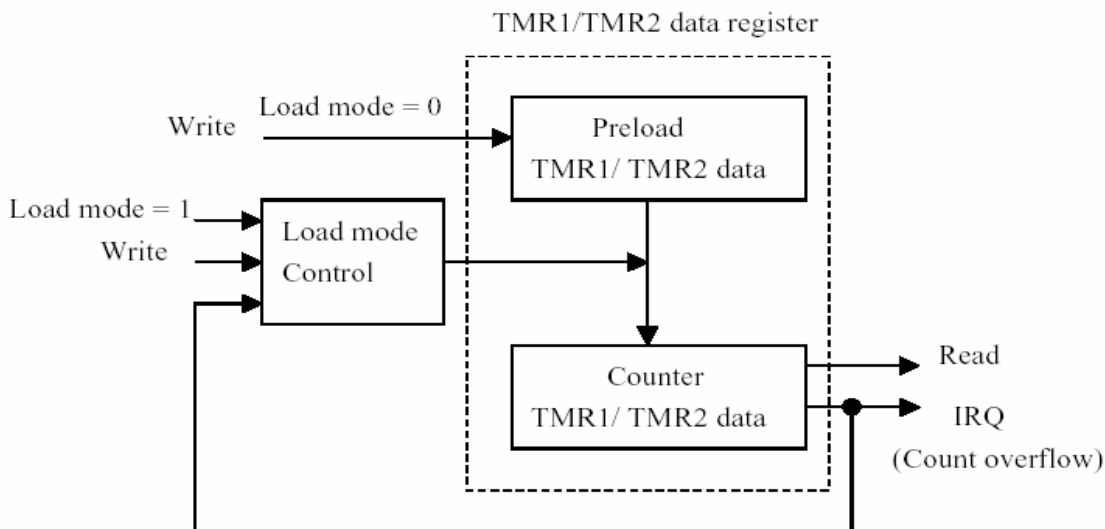


FIG. 1-5 TMR1/TMR2 Data register (timer/preloader)

3. TMR2 interrupt

There are four special function registers (SFR) associated with its operation, namely the IRQM (Interrupt Mask Register, its address is 21H), the IRQF (Interrupt Flag Register, its address is 22H), TRM2Control, which is the control register of TMR2 (with the address of 25H), and TMR2Preload, which is the data register of TMR2 (with the address of 27H); the four SFRs are defined as follows:

Control register TMR2 Control (25H)					
Address	Symbol	Description			
7	TMR2EN	TMR2 enable input: 1: TMR2 enable 0: TMR2 disable			
6	LOAD	TMR2 data loading mode: 1: When data is being written into TMR2 Preload register (TMR2_PRELOAD, 27H), the content of TMR2 is loaded immediately (default). 0: When data is being written into TMR2 Preload register (TMR1_PRELOAD, 26H), its value is not loaded until there is a count overflow in TMR2.			
5	SUR1	SUR1 SUR0	TMR2 clock source		
4	SUR0	0	0	Sourced from system time (only applicable in CRYSTAL mode)(NOTE<5>)	
		0	1	Sourced from EXT_CLK	
		1	0	Sourced from TMR1 (Connected to form a 16bit timer)	
		1	1	Not executed	
3	EDGE2	EDGE2: Sourced from the edge control bit in the TMR2 clock signal of EXT_CLK. 1: When EXT_CLK signal changes from high → low, TMR2 plus 1 0: When EXT_CLK signal changes from low → high, TMR2 plus 1			
2~0	PS2~PS0	PS2	PS1	PS0	TMR2 Prescaler
		0	0	0	1: 1
		0	0	1	1: 2
		0	1	0	1: 4
		0	1	1	1: 8
		1	0	0	1: 16
		1	0	1	1: 32
		1	1	0	1: 64
1	1	1	1: 128		

FIG. 1-6 TMR2 Control register

Control register TMR1, TMR2 Preload register (26H, 27H)		
Address	Symbol	Description
7~0	D7~D0	TMR1 and TMR2 Preload data register Default data value: D7~ D0 = FFH

FIG. 1-7 TMR1 and TMR2 Preload data register

NOTE:

- <1> TMR2 counts down, and data overflow occurs after the value becomes 00, then the hardware sets TMR2F to 1 in order to enter an interrupt.
- <2> During programming, special attention should be directed to the storage of variables when entering an interrupt; as well as the restoration of variables when exiting an interrupt.
- <3> The time for generating an interrupt = $1/4 * tmr2 \text{ prescaler rate} * tmr1 \text{ preload seconds}$.
- <4> When entering an interrupt, the value of TMR2Preload does not need to be reloaded.
the already defined value in the preload register will be automatically reloaded into the timer register.
- <5> The setting of Tmr2 data mode for the TMR2Control register:
when it is 1 (default) and there is data to be written into the register, the count value of TMR2 changes immediately. When it is 0 and there is data to be written into the register, the data can only be written into the register after a count overflow of TMR2 has occurred. As shown in the following diagram:

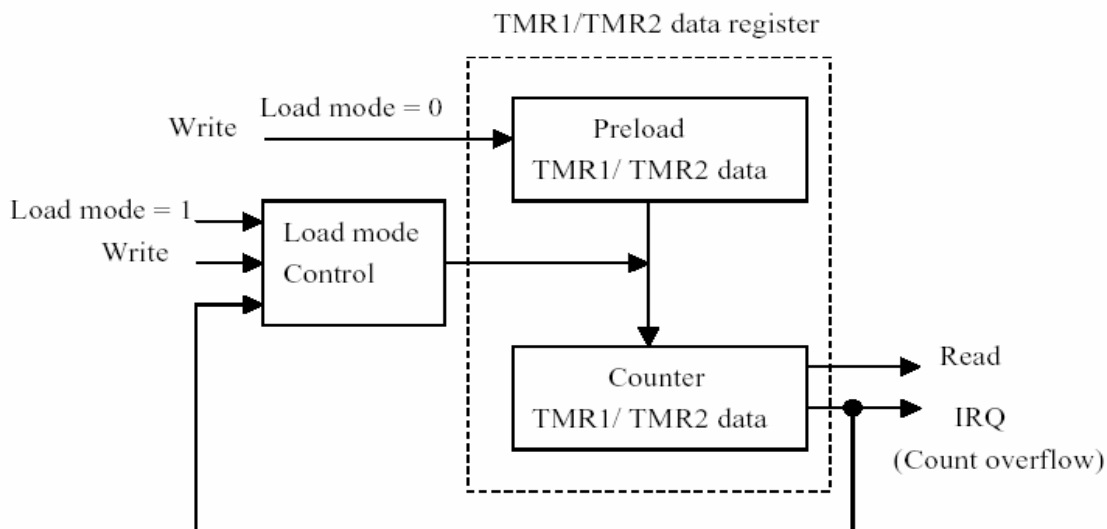


FIG. 1-5 TMR1/TMR2 Data register (timer/preloader)

4. Combining TMR1 and TMR2 interrupts (TMR1 Source from TMR2):

There are six types of SFR that are related to this mode of interrupt: they are the IRQM (Interrupt Mask Register, its address is 21H), the IRQF (Interrupt Flag Register, its address is 22H), TRM1Control, which is the control register of TMR1 (with the address of 24H), TMR1Preload, which is the data register of TMR1 (with the address of 26H), TRM2Control, which is the control register of TMR2 (with the address of 25H), and TMR2Preload, which is the data register of TMR2 (with the address of 27H).

NOTE:

- <1> Under this mode, TMR2Control[5 : 4] should be fixed at 0 0, which means TMR2 Source originates from System CLK (Only Crystal mode), whereas [5:4] should be fixed at 1 0, which means TMR1 Source originates from TMR2.
- <2> Under this mode, the prescale frequency of tmr2 can be selected by setting the tmr2 control register, but the prescale frequency of tmr1 can only be fixed at 1:1.
- <3> The time for generating an interrupt = $1/4M * ((tmr1preload - 1) * 256 + tmr2preload) * tmr2prescaler$ rate seconds.
- <4> When entering an interrupt, the values of TMR1Preload and TMR2Preload do not need to be re-loaded.

5. Combining TMR2 and TMR1 interrupts (TMR2 Source from TMR1):

There are six types of SFR associated with its operation, namely the IRQM (Interrupt Mask Register, its address is 21H), the IRQF (Interrupt Flag Register, its address is 22H), TRM1Control, which is the control register of TMR1 (with the address of 24H), TMR1Preload, which is the data register of TMR1 (with the address of 26H), TRM2Control, which is the control register of TMR2 (with the address of 25H), and TMR2Preload, which is the data register of TMR2 (with the address of 27H).

NOTE:

- <1> Under this mode, TMR1Control[5 : 4] should be fixed at 0 0, which means TMR1 Source originates from System CLK (Only Internal RC or External RC), whereas TMR2Control[5:4] should be fixed at 1 0, which means TMR2 Source originates from TMR1.
- <2> Under this mode, the prescale frequency of TMR1 can be selected by setting the TMR1 control register, but the prescale frequency of TMR2 can only be fixed at 1:1.
- <3> The time for generating an interrupt = $1/4M * ((tmr2preload - 1) * 256 + tmr1preload) * tmr1prescaler$ rate seconds.
- <4> When entering an interrupt, the values of TMR1Preload and TMR2Preload do not need to be re-loaded.

Examples will be used to explain the different types of interrupts in the following sections:

Ex. 1: Using the TMR0 interrupt

Program function: By using PORTB, 0 PIN to control LED to flash at the speed of approximately 1Hz (bright 500mS, dark 500mS).

(Diagram of the applicable circuit Y 2)

Firstly, it is necessary to select simulation and set up the configuration for the hardware of WDT within CONFIG WORD.

```

,,,,,,,,,,,,,,,,,,,,,,,,,,,,,configuration word,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
;TYPE=Advanced ,CLOCK=SINGLE,NT
;WDTE=Disable ,CPT=ON,LV=Don't use
;RESETB0=PA0 be normal I/O pin
;RESETB1=RESETB(PA5)be input pin
;IOC=OSC1,2 be clock pin
;AUP=Enable auto update page in advance mode
;INRC_FREQ=4M
;WORK_VOLTAGE=5V

```

```

,,,,,,,,,,,,,,,,,,,,,,,,,,,,,Register Definitions,,,,,,,,,,,,,,,,,,,,,,,,,,,,,

```

```

;-----special register-----

```

IAR	EQU	00H
TMR0	EQU	01H
PC	EQU	02H
STATUS	EQU	03H
BSR	EQU	04H
PORTA	EQU	05H
PORTB	EQU	06H
PULL_HI	EQU	20H
IRQM	EQU	21H
IRQF	EQU	22H
WDTSEL	EQU	23H
TMR1CONTROL	EQU	24H
TMR2CONTROL	EQU	25H
TMR1PRELOAD	EQU	26H
TMR2PRELOAD	EQU	27H
WAKE_UP	EQU	40H

```

;-----STATUS REGISTER BIT-----

```

C	EQU	0
DC	EQU	1
Z	EQU	2
PDB	EQU	3
TOB	EQU	4
SA0	EQU	5
A8	EQU	6

```

;-----IRQM REGISTER BIT-----

```

TIMR0M	EQU	0
EXINTM0	EQU	1
EXINTM1	EQU	2
TMR1M	EQU	4
TMR2M	EQU	5
INTM	EQU	7

```

;-----IRQF REGISTER BIT-----

```

TMR0F	EQU	0
EXINTF0	EQU	1
EXINTF1	EQU	2
TMR1F	EQU	4

```

TMR2F          EQU 5
;-----INSTRUCTION FLAG-----
A              EQU 0
M              EQU 1
;-----GENPORTA1 REGISTER -----
ACC_BUF       EQU 07H
STATUS_BUF    EQU 08H
COUNT        EQU 09H

```

```

;***** PROGRAM STARTS *****
;

```

```

        ORG          3FEH
        LGOTO        INTERRUPT
        ORG          3FFH
        LGOTO        MAIN
;-----
MAIN:   ORG          00H
        CLRM         ACC_BUF
        CLRM         STATUS_BUF
        CLRM         COUNT

        MOVLA        B'00000000'
        IODIR        PORTB
        CLRM         PORTB

        MOVLA        B'00000111'      ; TMR0 PRESCALE FREQUENCY 1 : 256
        MOVAM        IRQM

        MOVLA        .191
        MOVAM        TMR0
        MOVLA        B'10000001'      ; TMR0 INTERRUPT ENABLE
        MOVAM        IRQM
LOOP:   LGOTO        LOOP

```

```

;-----
THE TIME FOR GENERATING AN INTERRUPT=1/4M * 4 * 256 * (256-191)=0.01664S

```

```

INTERRUPT:
        MOVAM        ACC_BUF          ; STORING ACC AND STATUS
                                         REGISTER VALUES
        SWAPM        STATUS,A
        MOVAM        STATUS_BUF
        MOVLA        .191
        MOVAM        TMR0
        INCM         COUNT,M
        MOVLA        .30
        XORAM        COUNT,A          ; 0.016664*30=0.4992S(CLOSE TO
                                         500mS)
        BTMSS        STATUS,Z

```

```

    LGOTO      INTERRUPT_END
    CLRM
    MOVLA     B'00000001'
    XORAM     PORTB,M      ; 500mS IS UP, CHANGES THE STATUS
                           OF PORTB TO 0

INTERRUPT_END:
    BCM      IRQF,TMR0F
    SWAPM    STATUS_BUF,A
    MOVAM    STATUS      ; RESTORING ACC AND STATUS
                           REGISTER VALUES BEFORE THE
                           INTERRUPT

    MOVM     ACC_BUF,A
    RETI

-----
    END

```

Ex. 2: Using the TMR1 interrupt

Program function: By using PORTB, 0 PIN to control LED to flash at the speed of approximately 1Hz (bright 500mS, dark 500mS).

(Diagram of the applicable circuit Y 1)

Firstly, it is necessary to select simulation and set up the configuration for the hardware of WDT within CONFIG WORD.

```

,,,,,configuration word,,,,,
;TYPE=Advanced ,CLOCK=SINGLE ,external RC
;WDTE=Disable, CPT=ON,LV=Don't use
;RESETB0=PA0 be normal I/O pin
;RESETB1=RESETB(PA5)be input pin
;IOC=OSC1,2 be clock pin
;AUP=Enable auto update page in advance mode
;INRC_FREQ=4M
;WORK_VOLTAGE=5V

```

REGISTER DEFINITIONS:

SPECIAL REGISTER

```

IAR      EQU 00H
TMR0     EQU 01H
PC       EQU 02H
STATUS  EQU 03H
BSR     EQU 04H
PORTA   EQU 05H
PORTB   EQU 06H
PULL_HI EQU 20H
IRQM    EQU 21H
IRQF    EQU 22H
WDTSEL  EQU 23H
TMR1CONTROL EQU 24H
TMR2CONTROL EQU 25H
TMR1PRELOAD EQU 26H

```

```
TMR2PRELOAD EQU 27H
WAKE_UP      EQU 40H
```

```
;-----STATUS REGISTER BIT-----
```

```
C EQU 0
DC EQU 1
Z EQU 2
PDB EQU 3
TOB EQU 4
SA0 EQU 5
A8 EQU 6
```

```
;-----IRQM REGISTER BIT-----
```

```
TMR0M EQU 0
EXINTM0 EQU 1
EXINTM1 EQU 2
TMR1M EQU 4
TMR2M EQU 5
INTM EQU 7
```

```
;-----IRQF REGISTER BIT-----
```

```
TMR0F EQU 0
EXINTF0 EQU 1
EXINTF1 EQU 2
TMR1F EQU 4
TMR2F EQU 5
```

```
;-----INSTRUCTION FLAG-----
```

```
A EQU 0
M EQU 1
```

```
;-----GENEPORTA1 REGISTER -----
```

```
ACC_BUF EQU 07H
STATUS_BUF EQU 08H
COUNT EQU 09H
```

```
***** PROGRAM STARTS *****
```

```
;-----
ORG 3FEH
LGOTO INTERRUPT
ORG 3FFH
LGOTO MAIN
;-----
ORG 00H
MAIN
CLRM ACC_BUF
CLRM STATUS_BUF
CLRM COUNT

MOVLA B'00000000'
IODIR PORTB
CLRM PORTB

MOVLA B'10010000' ; TMR1 INTERRUPT ENABLE
MOVAM IRQM
```

```

MOVLA      .130
MOVAM      TMR1PRELOAD
MOVLA      B'11000111'      ; TMR1 PRESCALE FREQUENCY
                                1 : 128
MOVAM      TMR1CONTROL      ; TMR1 FROM EXTERNAL RC
LOOP:
LGOTO      LOOP

```

THE TIME FOR GENERATING AN INTERRUPT = $1/4 * 128 * 130 = 0.00416$ S

```

-----
INTERRUPT:
MOVAM      ACC_BUF          ; STORING ACC AND STATUS
                                REGISTER VALUES

SWAPM      STATUS,A
MOVAM      STATUS_BUF
INCM       COUNT,M
MOVLA      .120
XORAM      COUNT,A          ; 0.00416*120=0.4992S(CLOSE TO
                                500mS)

BTMSS      STATUS,Z
LGOTO      INTERRUPT_END
CLRM       COUNT
MOVLA      B'00000001'
XORAM      PORTB,M          ; 500mS IS UP, CHANGES THE STATUS
                                OF PORTB TO 0

INTERRUPT_END:
BCM        IRQF,TMR1F
SWAPM      STATUS_BUF,A
MOVAM      STATUS          ; RESTORING ACC AND STATUS
                                REGISTER VALUES BEFORE THE
                                INTERRUPT

MOVAM      ACC_BUF,A
RETI

-----
END

```

Ex. 3: Using the TMR2 interrupt

Program function: By using PORTB, 0 PIN to control LED to flash at the speed of approximately 1Hz (bright 500mS, dark 500mS).

(Diagram of the applicable circuit Y_2)

Firstly, it is necessary to select simulation and set up the configuration for the hardware of WDT within CONFIG WORD.

```

,,,,,,,,,,,,,configuration word,,,,,,,,,,,,,
;TYPE=Advanced ,CLOCK=NT
;WDTE=Disable ,CPT=ON,LV=Don't use
;RESETB0=PA0 be normal I/O pin
;RESETB1=RESETB(PA5)be input pin
;IOC=OSC1,2 be clock pin

```

```
;AUP=Enable auto update page in advance mode
;INRC_FREQ=4M
;WORK_VOLTAGE=5V
```

```
-----
;REGISTER DEFINITIONS:-----
```

```
-----SPECIAL REGISTER -----
```

```
IAR          EQU 00H
TMR0         EQU 01H
PC           EQU 02H
STATUS      EQU 03H
BSR         EQU 04H
PORTA       EQU 05H
PORTB       EQU 06H
PULL_HI     EQU 20H
IRQM        EQU 21H
IRQF        EQU 22H
WDTSEL      EQU 23H
TMR1CONTROL EQU 24H
TMR2CONTROL EQU 25H
TMR1PRELOAD EQU 26H
TMR2PRELOAD EQU 27H
WAKE_UP     EQU 40H
```

```
-----STATUS REGISTER BIT-----
```

```
C           EQU 0
DC          EQU 1
Z           EQU 2
PDB        EQU 3
TOB        EQU 4
SA0        EQU 5
A8         EQU 6
```

```
-----IRQM REGISTER BIT-----
```

```
TIMR0M     EQU 0
EXINTM0    EQU 1
EXINTM1    EQU 2
TMR1M      EQU 4
TMR2M      EQU 5
INTM       EQU 7
```

```
-----IRQF REGISTER BIT-----
```

```
TMR0F      EQU 0
EXINTF0    EQU 1
EXINTF1    EQU 2
TMR1F      EQU 4
TMR2F      EQU 5
```

```
-----INSTRUCTION FLAG-----
```

```
A          EQU 0
M          EQU 1
```

```
-----GENEPORTA1 REGISTER -----
```

```
ACC_BUF    EQU 07H
```

```
STATUS_BUF EQU 08H
COUNT EQU 09H
```

***** PROGRAM STARTS *****

```
ORG 3FEH
LGOTO INTERRUPT
ORG 3FFH
LGOTO MAIN
ORG 00H
MAIN
CLRM ACC_BUF
CLRM STATUS_BUF
CLRM COUNT

MOVLA B'00000000'
IODIR PORTB
CLRM PORTB

MOVLA B'10100000' ; TMR2 INTERRUPT ENABLE
MOVAM IRQM

MOVLA .130
MOVAM TMR2PRELOAD
MOVLA B'11000111' ; TMR2 PRESCALE FREQUENCY
; 1 : 128
MOVAM TMR2CONTROL ; TMR2 FROM CRYSTAL OSCILLATION
MODE
LOOP:
LGOTO LOOP
```

THE TIME FOR GENERATING AN INTERRUPT = $1/4 * 128 * 130 = 0.00416$ S

```
INTERRUPT:
MOVAM ACC_BUF ; STORING ACC AND STATUS
REGISTER VALUES
SWAPM STATUS,A
MOVAM STATUS_BUF
INCM COUNT,M
MOVLA .120 ; AFTER 120 TIMES OF INTERRUPTS,
THESTATUS OF PORTB, 0 IS
CHANGED
XORAM COUNT,A ; 0.00416*120=0.4992S
(CLOSE TO 500mS)
BTMSS STATUS,Z
LGOTO INTERRUPT_END
CLRM COUNT
MOVLA B'00000001'
XORAM PORTB,M ; 500mS IS UP, CHANGES THE STATUS
```

```

                                OF PORTB TO 0
INTERRUPT_END:
    BCM          IRQF,TMR2F
    SWAPM        STATUS_BUF,A
    MOVAM        STATUS          ; RESTORING ACC AND STATUS
                                REGISTER VALUES BEFORE THE
                                INTERRUPT
    MOVM         ACC_BUF,A
    RETI
-----
    END
; =====

```

Ex. 4: Combining TMR1 and TMR2 interrupts (TMR1 sources from TMR2)
 Program function: By using PORTB, 0 PIN to control LED to flash at the speed of approximately 1Hz (bright 500mS, dark 500mS).

(Diagram of the applicable circuit Y 2)

Firstly, it is necessary to select simulation and set up the configuration for the hardware of WDT within CONFIG WORD.

```

,,,,,,configuration word,,,,,,
;TYPE=Advanced ,CLOCK=NT
;WDTE=Disable ,CPT=ON,LV=Don't use
;RESETB0=PA0 be normal I/O pin
;RESETB1=RESETB(PA5)be input pin
;IOC=OSC1,2 be clock pin
;AUP=Enable auto update page in advance mode
;INRC_FREQ=4M
;WORK_VOLTAGE=5V
; =====

```

-----;REGISTER DEFINITIONS:-----

-----SPECIAL REGISTER -----

```

IAR          EQU 00H
TMR0         EQU 01H
PC           EQU 02H
STATUS       EQU 03H
BSR         EQU 04H
PORTA        EQU 05H
PORTB        EQU 06H
PULL_HI     EQU 20H
IRQM         EQU 21H
IRQF         EQU 22H
WDTSEL       EQU 23H
TMR1CONTROL  EQU 24H
TMR2CONTROL  EQU 25H
TMR1PRELOAD  EQU 26H
TMR2PRELOAD  EQU 27H
WAKE_UP     EQU 40H

```

-----STATUS REGISTER BIT-----

```

C           EQU 0

```

```

DC          EQU 1
Z           EQU 2
PDB        EQU 3
TOB        EQU 4
SA0        EQU 5
A8         EQU 6
;-----IRQM REGISTER BIT-----
TIMR0M     EQU 0
EXINTM0    EQU 1
EXINTM1    EQU 2
TMR1M      EQU 4
TMR2M      EQU 5
INTM       EQU 7
;-----IRQF REGISTER BIT-----
TMR0F      EQU 0
EXINTF0    EQU 1
EXINTF1    EQU 2
TMR1F      EQU 4
TMR2F      EQU 5
;-----INSTRUCTION FLAG-----
A          EQU 0
M          EQU 1
;-----GENEPORTA1 REGISTER -----
ACC_BUF    EQU 07H
STATUS_BUF EQU 08H
COUNT     EQU 09H

```

```

***** PROGRAM STARTS *****
;
      ORG          3FEH
      LGOTO        INTERRUPT
      ORG          3FFH
      LGOTO        MAIN
;-----
      ORG          00H
MAIN
      CLRM         ACC_BUF
      CLRM         STATUS_BUF
      CLRM         COUNT

      MOVLA        B'00000000'
      IODIR        PORTB
      CLRM         PORTB

      MOVLA        B'10010000'           ;TMR1 INTERRUPT ENABLE
      MOVAM        IRQM

      MOVLA        B'01100000'           ;TMR1 PRESCALE FREQUENCY
                                           1 : 1
      MOVAM        TMR1CONTROL           ;TMR1 SOURCE FROM

```

TMR2(CONNECTED TO TMR2 TO
FORM A 16BIT TIMER)

```

MOVLA      B'01000111'      ;TMR2 PRESCALE FREQUENCY
                                1 : 128
MOVAM      TMR2CONTROL      ; TMR2 FROM CRYSTAL
                                OSCILLATION
MOVLA      09H
MOVAM      TMR2PRELOAD
MOVLA      03H
MOVAM      TMR1PRELOAD
BSM        TMR2CONTROL,7
BSM        TMR1CONTROL,7
LOOP:
LGOTO     LOOP

```

THE TIME FOR GENERATING AN INTERRUPT = $1/4 * ((3-1) * 256+9) * 128 = 0.016672$ S

```

INTERRUPT:
MOVAM      ACC_BUF          ; STORING ACC AND STATUS
                                REGISTER VALUES
SWAPM      STATUS,A
MOVAM      STATUS_BUF
INCM       COUNT,M
MOVLA     .30
XORAM     COUNT,A          ; 0.016672*30=0.50016 S(CLOSE TO
                                500mS)
BTMSS     STATUS,Z
LGOTO     INTERRUPT_END
CLRM      COUNT
MOVLA     B'00000001'
XORAM     PORTB,M          ; 500mS IS UP, CHANGES THE STATUS
                                OF PORTB TO 0
INTERRUPT_END:
BCM        IRQF,TMR1F      ; CLEARS TMR1INTERRUPT FLAG
SWAPM     STATUS_BUF,A
MOVAM     STATUS          ; RESTORING ACC AND STATUS
                                REGISTER VALUES BEFORE THE
                                INTERRUPT
MOVAM     ACC_BUF,A
RETI

```

END

Ex. 5: Combining TMR2 and TMR1 interrupts (TMR2 sources from TMR1)

Program function: By using PORTB, 0 PIN to control LED to flash at the speed of approximately 1Hz (bright 500mS, dark 500mS).

(Diagram of the applicable circuit Y 2)

Firstly, it is necessary to select simulation and set up the configuration for the hardware of WDT within CONFIG WORD.

```

,,,,,,,,,,,,,,,,,,,,,configuration word,,,,,,,,,,,,,,,,,,,,,
;TYPE=Advanced ,CLOCK=SINGLE ,external RC
;WDTE=Disable ,CPT=ON,LV=Don't use
;RESETB0=PA0 be normal I/O pin
;RESETB1=RESETB(PA5)be input pin
;IOC=OSC1,2 be clock pin
;AUP=Enable auto update page in advance mode
;INRC_FREQ=4M
;WORK_VOLTAGE=5V

```

```

-----
;REGISTER DEFINITINOS:-----
;-----SPECIAL REGISTER-----

```

```

IAR          EQU 00H
TMR0         EQU 01H
PC           EQU 02H
STATUS      EQU 03H
BSR         EQU 04H
PORTA       EQU 05H
PORTB       EQU 06H
PULL_HI     EQU 20H
IRQM        EQU 21H
IRQF        EQU 22H
WDTSEL      EQU 23H
TMR1CONTROL EQU 24H
TMR2CONTROL EQU 25H
TMR1PRELOAD EQU 26H
TMR2PRELOAD EQU 27H
WAKE_UP     EQU 40H

```

```

;-----STATUS REGISTER BIT-----

```

```

C           EQU 0
DC          EQU 1
Z           EQU 2
PDB        EQU 3
TOB        EQU 4
SA0        EQU 5
A8         EQU 6

```

```

;-----IRQM REGISTER BIT-----

```

```

TIMR0M     EQU 0
EXINTM0    EQU 1
EXINTM1    EQU 2
TMR1M      EQU 4
TMR2M      EQU 5
INTM       EQU 7

```

;-----IRQF REGISTER BIT-----

```
TMR0F      EQU 0
EXINTF0    EQU 1
EXINTF1    EQU 2
TMR1F      EQU 4
TMR2F      EQU 5
```

;-----INSTRUCTION FLAG-----

```
A          EQU 0
M          EQU 1
```

;-----GENEPORTA1 REGISTER -----

```
ACC_BUF    EQU 07H
STATUS_BUF EQU 08H
COUNT     EQU 09H
```

;***** PROGRAM STARTS *****

```
      ORG          3FEH
      LGOTO        INTERRUPT
      ORG          3FFH
      LGOTO        MAIN
-----
MAIN  ORG          00H

      CLRM         ACC_BUF
      CLRM         STATUS_BUF
      CLRM         COUNT

      MOVLA        B'00000000'
      IODIR        PORTB
      CLRM         PORTB

      MOVLA        B'10100000'          ; TMR2 INTERRUPT ENABLE
      MOVAM        IRQM

      MOVLA        B'01000111'          ;TMR1 PRESCALE FREQUENCY
                                          1 : 128
      MOVAM        TMR1CONTROL          ;TMR1 FROM EXTERNAL RC

      MOVLA        B'01000111'          ;TMR2 PRESCALE FREQUENCY
                                          1 : 1
      MOVAM        TMR2CONTROL          ;TMR2 FROM TMR1(CONNECTED
                                          TO TMR2 AND FORM A 16BIT
                                          TIMER)

      MOVLA        03H
      MOVAM        TMR2PRELOAD

      MOVLA        09H
      MOVAM        TMR1PRELOAD
```

```

    BSM          TMR2CONTROL,7
    BSM          TMR1CONTROL,7
LOOP:
    LGOTO       LOOP

```

THE TIME FOR GENERATING AN INTERRUPT = $1/4 * ((3-1) * 256+9) * 128 = 0.016672$ S

```

INTERRUPT:
    MOVAM       ACC_BUF          ; STORING ACC AND STATUS
                                ; REGISTER VALUES
    SWAPM       STATUS,A
    MOVAM       STATUS_BUF

    INCM        COUNT,M
    MOVLA       .30
    XORAM       COUNT,A          ; 0.016672*30=0.50016 S(CLOSE TO
                                ; 500mS)
    BTMSS       STATUS,Z
    LGOTO       INTERRUPT_END
    CLRM        COUNT
    MOVLA       B'00000001'
    XORAM       PORTB,M          ; 500MS IS UP, CHANGES THE STATUS
                                ; OF PORTB TO 0

INTERRUPT_END:
    BCM         IRQF,TMR2F       ; CLEARS TMR2 INTERRUPT FLAG
    SWAPM       STATUS_BUF,A
    MOVAM       STATUS          ; RESTORING ACC AND STATUS
                                ; REGISTER VALUES BEFORE THE
                                ; INTERRUPT

    MOVAM       ACC_BUF,A
    RETI

; =====

```

